

Parallel File Striping

Design trade-offs

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<http://visiblehuman.epfl.ch>

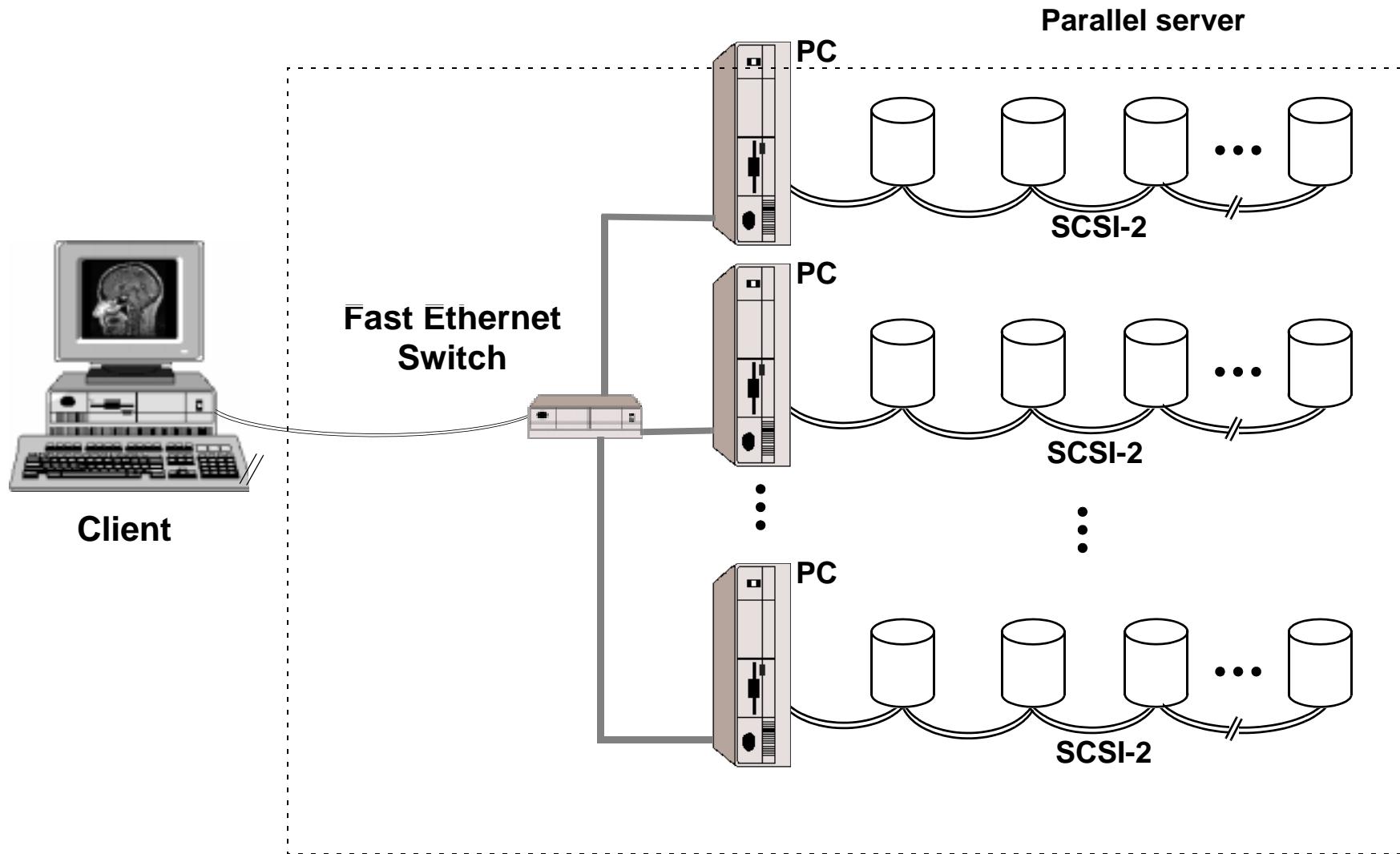
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1. Context

- **Parallel distributed memory servers
for I/O - & compute-intensive applications**
- **Assumptions:**
 - Parallel file striping library linked to application
 - Local files are standard files (NT, Unix)
- **Goal: make maximal use of underlying hardware and software :**
 - => **Simultaneous I/O accesses,
communications and computations**
 - => **Generate asynchronous schedule of operations**

Considered Architecture



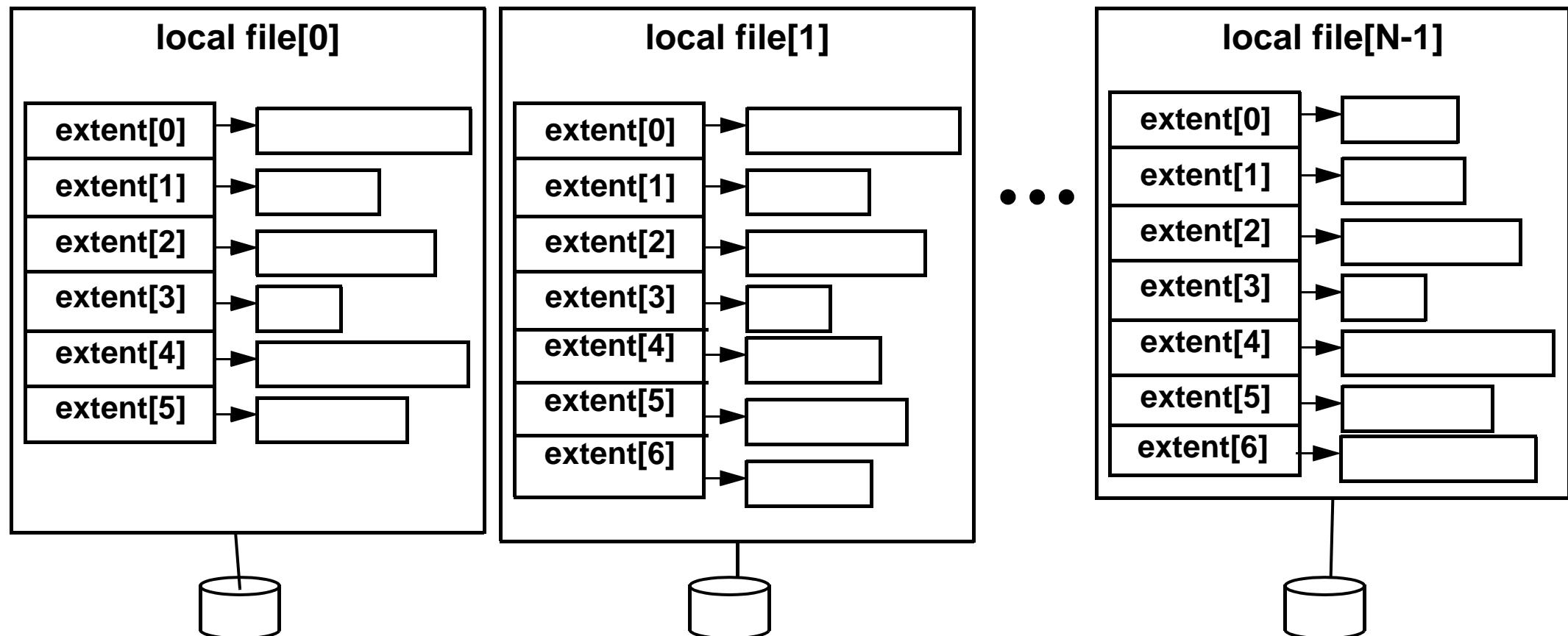
2. I/O Interface at the striped file level

- Generating asynchronous schedules with CAP (Computer-Aided Parallelization)
- Example: The Visible Human Slice Server
<http://visiblehuman.epfl.ch>
see next slices:
 - Pipelined parallel slice extraction
 - Performances
- Mapping specified by application:
Global file position
 - > LocalFileIndex
 - > LocalExtentIndexSystem library specified mapping
LocalFileIndex -> DiskServerIndex
DiskServerIndex -> ComputeServerIndex
- Programmer must deal with 4 indices
Advantages:
 - When possible, computations on same node as disk data
 - Simultaneous computations & disk accesses (programmable prefetching strategy)
 - Disk directed I/O feasible, i.e. disk server may request data from appl. processes

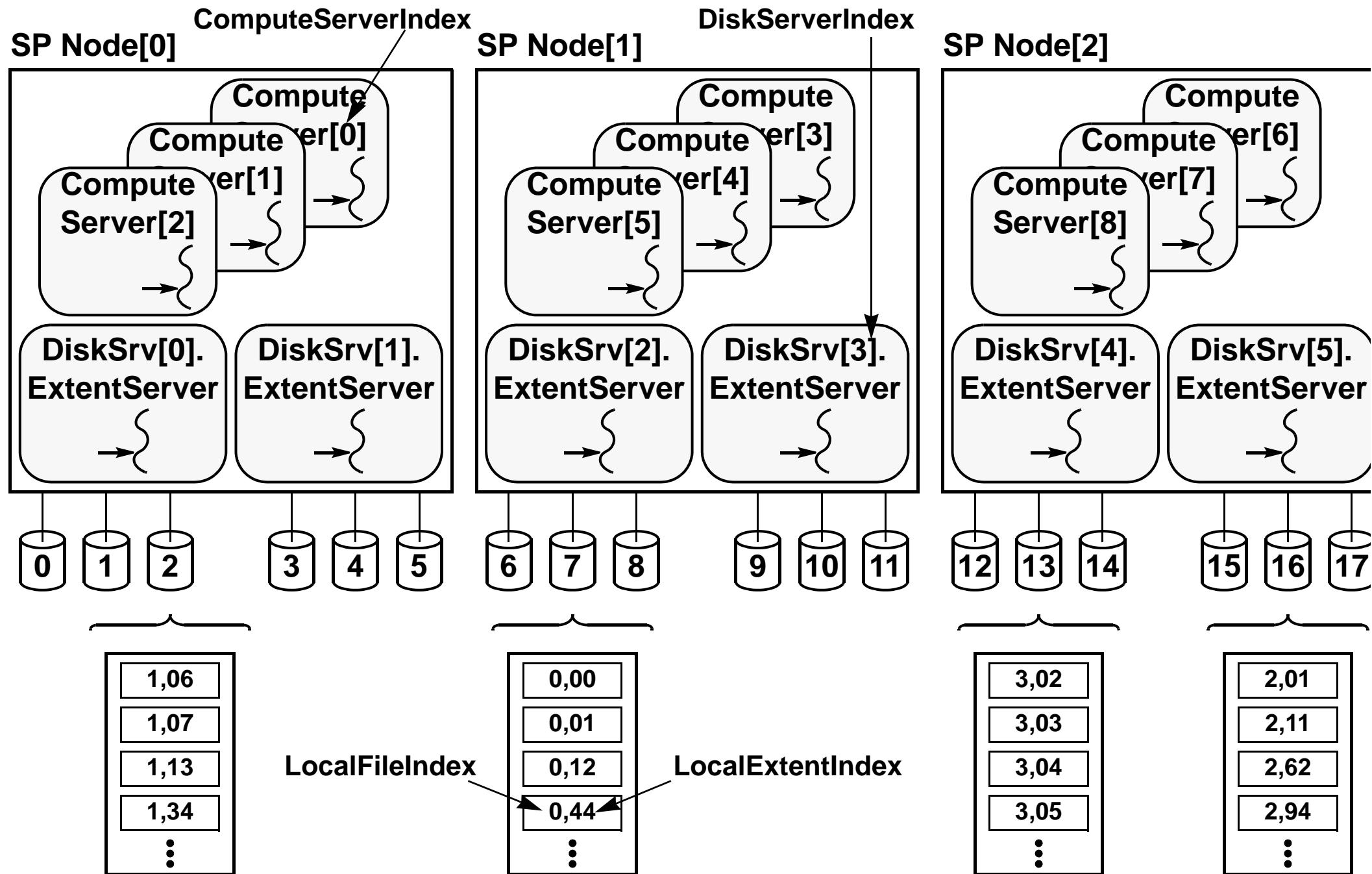
Two-Dimensional Parallel File Structure

extent location given by <LocalFileIndex, LocalExtentIndex>

parallel file declustered across N local files (disks)



LocalFileIndex, LocalExtentIndex, DiskServerIndex & ComputeServerIndex

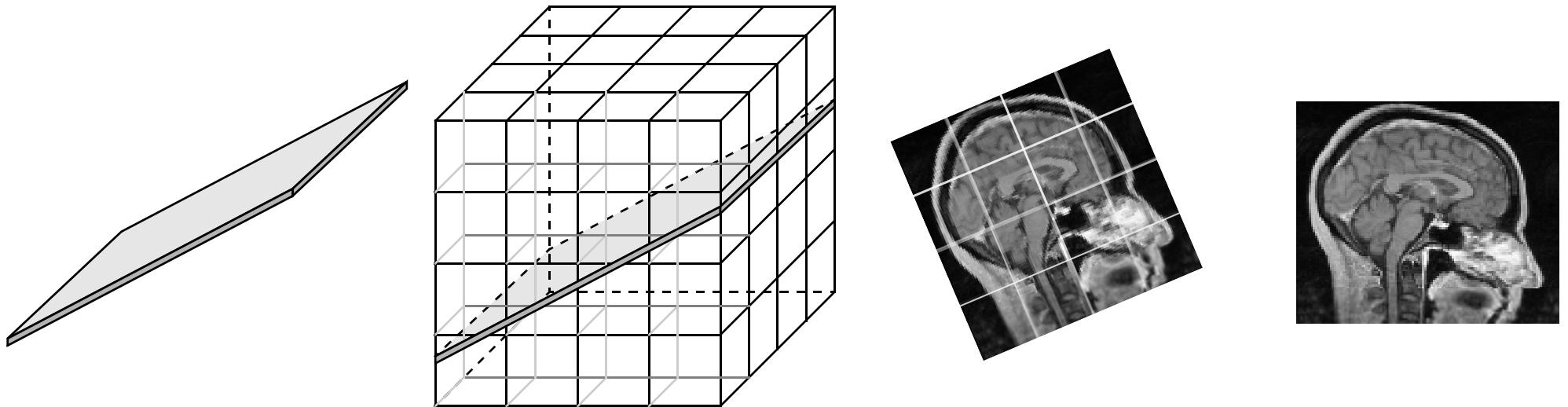


Example: the Visible Human Slice Server

(<http://visiblehuman.epfl.ch>)

- Human Male: 13 GB of data striped over 60 disks (sub-volumes: file extents)**
- Resolution: one anatomical slice/mm in each anatomical slice: 3 samples/mm**
- Size: 1840 horizontal slices, each 2048x1216 pixels**
- Software :**
 - client sends slice position & orientation**
 - server interface asks for subslices**
 - server processors read sub-volumes, extract and project slices (resampling)**
 - server interface assembles resulting full slice, compresses it and sends it to client**

Extraction of Slice Parts from Volumic File Extents



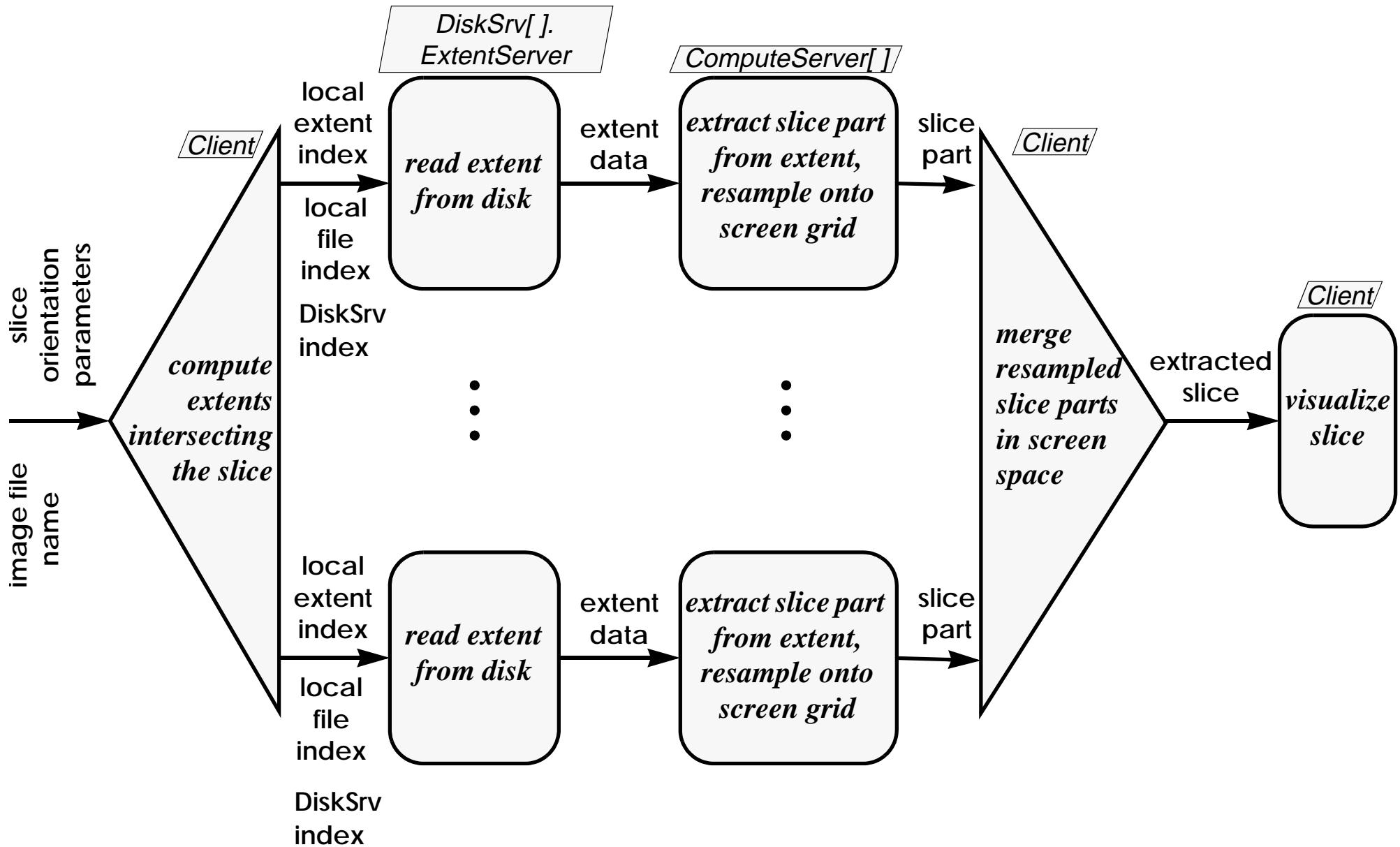
Extraction slice
specification

Extraction of the
digital slice from
the 3D image

Extracted
slice parts

Resampled slice
parts merged into
the final
displayable slice

Pipelined Parallel Slice Extraction



CAP Specification of the Pipelined Parallel Slice Extraction

```
1 leaf operation Ps2ExtentServerT::ReadExtent
2   in ExtentReadingRequestT* InputP
3   out ExtentT* OutputP;
4
5 leaf operation Ps2ComputeServerT::ExtractAndResampleSlicePart
6   in ExtentT* InputP
7   out SlicePartT* OutputP
8 { ...C++ sequential code }
9
10 bool SplitsSliceRequest(SliceExtractionRequestT* FromP,
11                         ExtentReadingRequestT* PreviousP,
12                         ExtentReadingRequestT* &ThisP)
13 {
14   ...C++ sequential code
15   return ( IsNotLastExtentReadingRequest );
16 }
17
18 void MergeSlicePart(SliceT* IntoP, SlicePartT* ThisP)
19 {
20   ...C++ sequential code
21 }
22
23 operation Ps2ServerT::ExtractSlice
24   in SliceExtractionRequestT* InputP
25   out SliceT* OutputP
26 {
27   parallel while (SplitsSliceRequest, MergeSlicePart, Client, SliceT Output)
28   (
29     DiskSrv[thisTokenP->DiskServerIndex].ExtentServer.ReadExtent
30     >->
31     ComputeServer[thisTokenP->ComputeServerIndex].ExtractAndResampleSlicePart
32   )
33 }
```

see <http://diwww.epfl.ch/w3lsp/pub/publications/gigaview/captutorial.pdf>

Visible Human Slice Extraction Performances

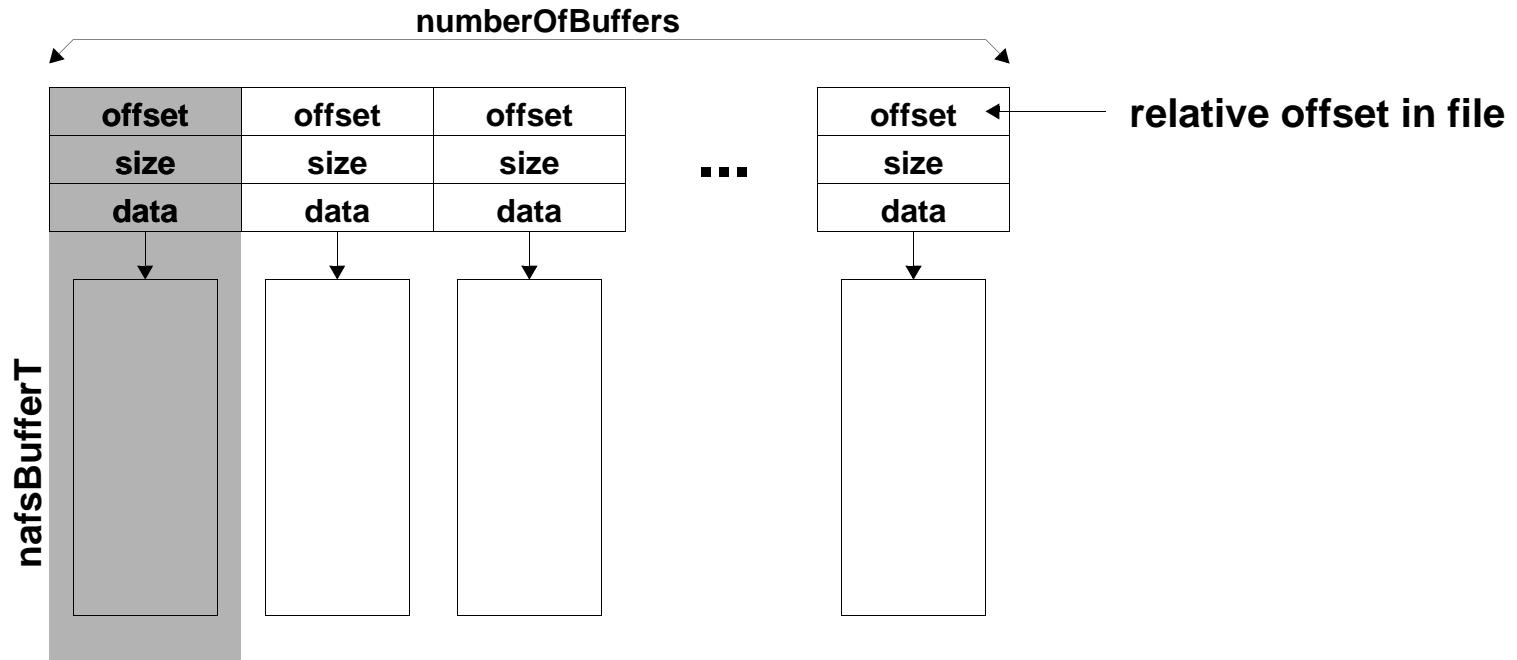
- **Max. configuration, caches disabled**
5 server PC's, each with 12 disks
4.8 extracted slices/s
client processor utilization: 85%
=> 104 MB/s read from 60 disks
=> mean throughput per disk 1.74 MB/s
=> disks are bottleneck

3. High-level Striped File Interface (NAFS)

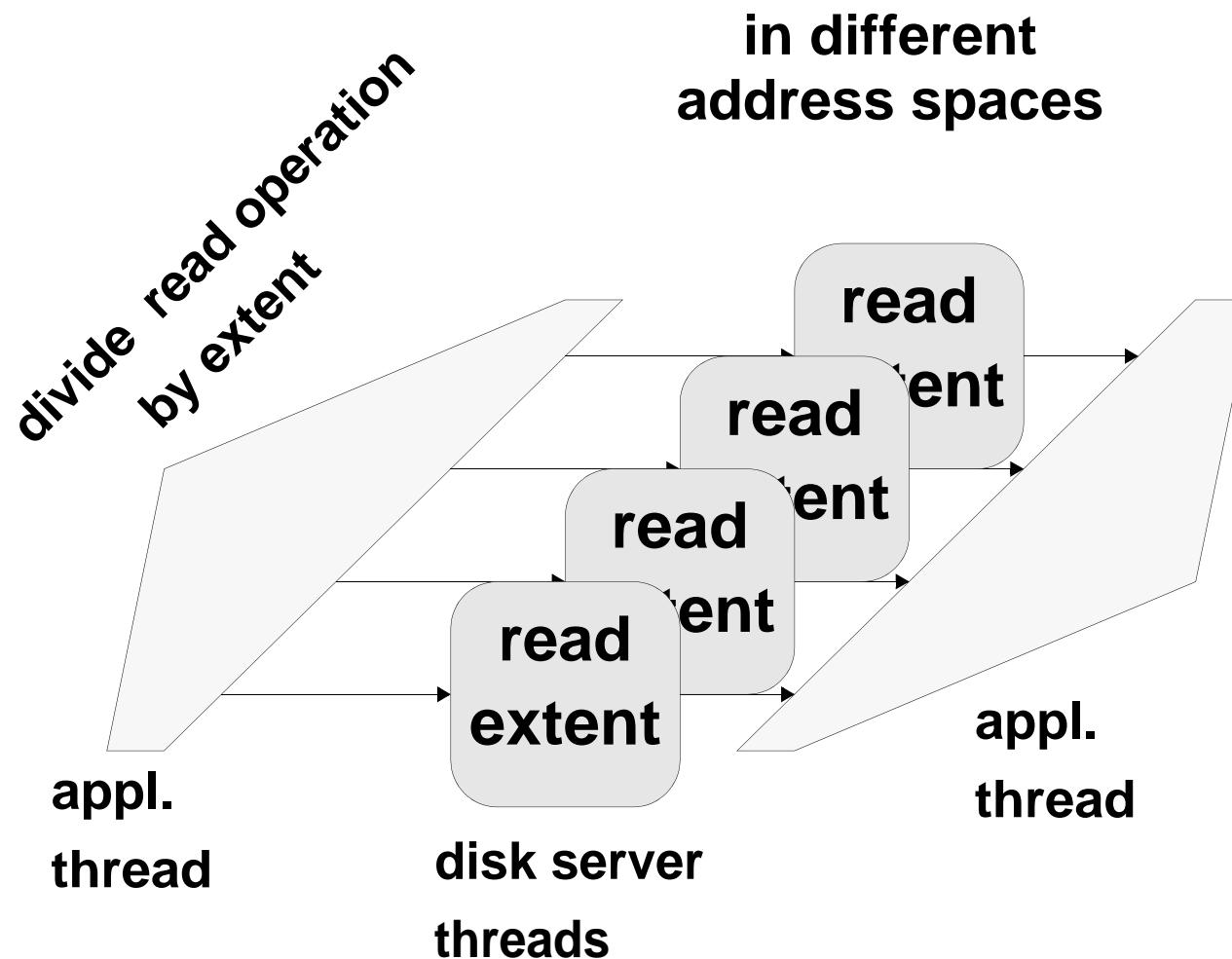
- Interface translates global byte positions to LocalFileIndices, LocalExtentIndices and local byte positions
- User specified stripe unit, striping over a set of user specified paths (disks).
- Read, Write, CollectiveRead, CollectiveWrite of a set of contiguous data buffers
- Assessment: Simple interface, but no direct knowledge about locality of data

High-level striped file interface (NAFS)

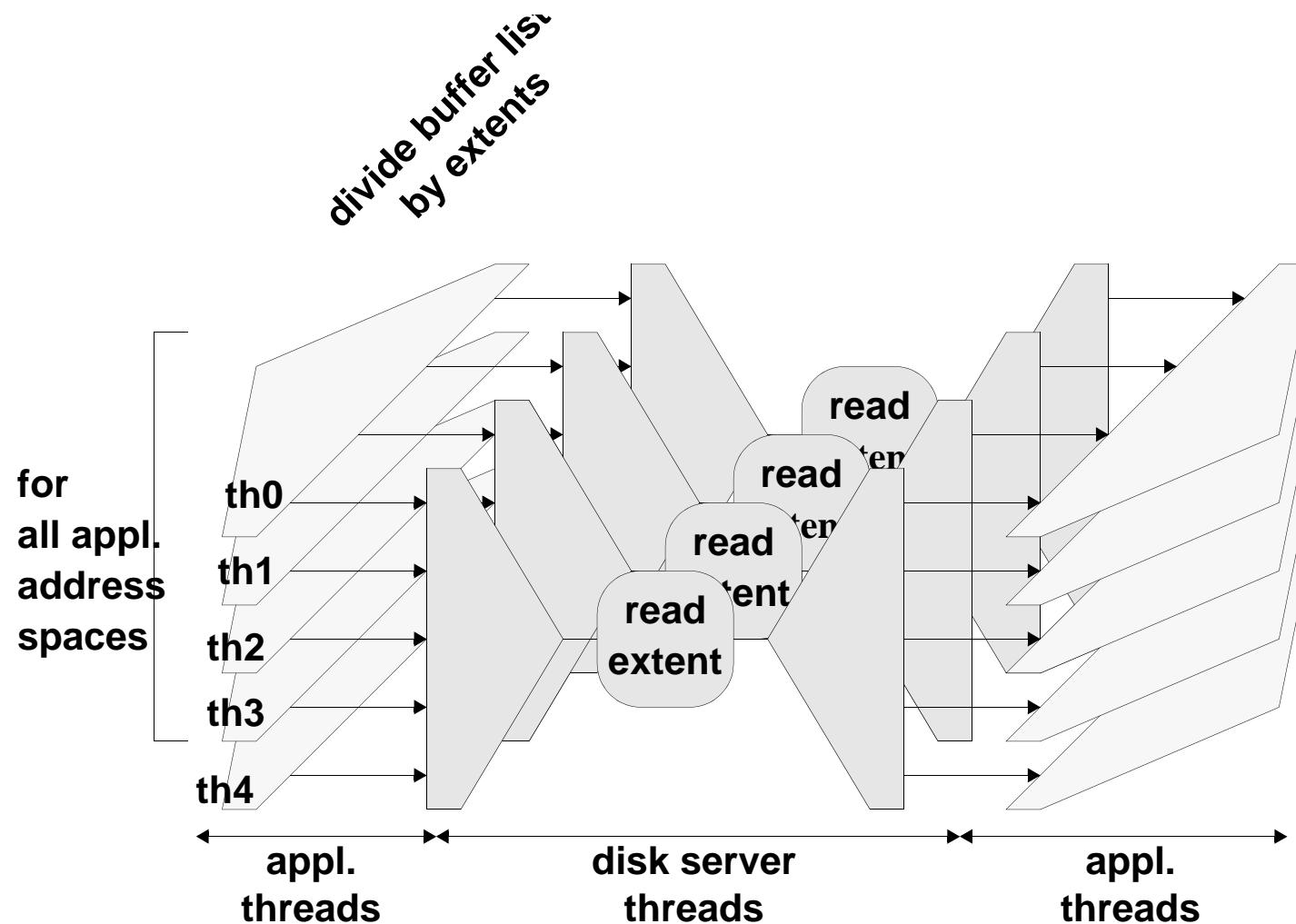
```
nafsFileT* nafsOpen (char* fileNameS, char openMode) ;  
int nafsClose (nafsFileT* fileP) ;  
int nafsCreate (char* fileNameS) ;  
int nafsDelete (char* fileNameS) ;  
int nafsWrite (nafsFileT* fileP, UINT64_T absoluteOffsetInFile,  
               UINT32_T numberOfBuffers, nafsBufferT* buffersP) ;  
int nafsRead (nafsFileT* fileP, UINT64_T absoluteOffsetInFile,  
              UINT32_T numberOfBuffers, nafsBufferT* buffersP) ;  
int nafsCollectiveWrite (nafsFileT* fileP, UINT64_T absoluteOffsetInFile,  
                        UINT32_T numberOfBuffers, nafsBufferT* buffersP) ;  
int nafsCollectiveRead (nafsFileT* fileP, UINT64_T absoluteOffsetInFile,  
                       UINT32_T numberOfBuffers, nafsBufferT* buffersP) ;
```



Read operation



Collective read operation



4. Performance of the high-level Striped File Interface

- **Configuration:**
4 Bi-PentiumPro PC's, with 8 disks (5400 rpm), interconnected by Fast Ethernet switch
- **Writes to local disks:** $8 \times 2.5\text{MB/s} \Rightarrow 20\text{MB/s}$ (32KB data chunks), no much processing power used
- **Collective write:** each processor writes to each disk many 2KB data chunks
max sustainable Fast Ethernet throughput per PC: 4MB/s (100% processor utilization)
 $\Rightarrow 2\text{MB/s}$ for sending out data from application
2 MB/s for receiving data to the disks
 $\Rightarrow 2\text{MB/s}$ per node global write throughput
half the processing power used

5. Conclusions

- **As long as TCP-IP is used, minimize accesses to remote disks (low-level striped file interface)**
 - **Even for I/O fast communication network is required**
=> **Socket based interface, with flow control but without TCP-IP processing overhead**
 - **High-Performance File Server:**
TCP-IP data transfers considerably reduce effective RAID access bandwidth
=> **during computations, parallel I/O across a large number of nodes is preferable (SwissTx: 3MB/s per node expected)**
 - **After computation session, save striped files to file server**
pmv, pcp: parallel move or parallel copy
 - **In case of processor/disk failure, current results are lost; relaunch computation**
 - **Option: delayed generation of a parity file**
- RDH/March 23rd, 1999, SOS Workshop, Villard, Switzerland